

A Simpler Undecidability Proof for System \mathbf{F} Inhabitation

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Polymorphic λ -calculus (also known as Girard’s “system \mathbf{F} ” [3] or $\lambda 2$ [2]) is directly related to intuitionistic second-order propositional logic (IPC_2) via the Curry–Howard isomorphism (for an overview see [5]). In particular, provability in the implicational fragment of IPC_2 (is a given formula an IPC_2 theorem?) corresponds to inhabitation in system \mathbf{F} (given a type, is there a term having that type in system \mathbf{F} ?).

Provability in IPC_2 was shown by Löb to be undecidable [4]. The proof itself is by reduction from provability in first-order predicate logic via a semantic argument. Since the original proof is heavily condensed (14 pages), Arts in collaboration with Dekkers provided a fully unfolded argument [1] (approx. 50 pages) reconstructing the original proof. Later, Sørensen and Urzyczyn developed a different, syntax oriented proof showing undecidability of inhabitation in system \mathbf{F} [5, Section 11.6] (6 pages, moderately condensed).

In order to show undecidability of provability in IPC_2 , each of the above approaches embeds first-order predicate logic into IPC_2 . However, if one is solely interested in a concise and rigorous proof (e.g. for formalization or didactics), then there is no need for a full embedding. In fact, we can pursue a different approach to show undecidability of inhabitation in system \mathbf{F} . In this extended abstract, we sketch a reduction from solvability of Diophantine equations (is there an integer solution to $P(x_1, \dots, x_n) = 0$ where P is a polynomial with integer coefficients?) to inhabitation in system \mathbf{F} . We argue that, compared to the previous approaches, the sketched reduction is more accessible for formalization and more comprehensible for didactic purposes.

First, let us fix some notation. Let *type variables* be ranged over by a, b, c, \dots , we define *polymorphic types* ranged over by $\sigma, \tau, \rho, \dots$ as

$$\sigma, \tau, \rho ::= a \mid \sigma \rightarrow \tau \mid \forall a. \sigma$$

Let M, N, \dots be ranged over Church-style polymorphic λ -calculus terms defined as

$$M, N ::= x \mid (M N) \mid (\lambda x : \sigma. M) \mid (\Lambda a. M) \mid M \tau$$

Let $\Delta = \{x_1 : \sigma_1, \dots, x_n : \sigma_n\}$ denote finite *type environments*. Typing rules of system \mathbf{F} deriving *judgements* $\Delta \vdash M : \sigma$ are as usual [5, Section 11.2].

As a starting point, we use the following Problem 1, which is undecidable by reduction (routine polynomial decomposition) from solvability of Diophantine equations.

Problem 1. *Given a set $A = \{\epsilon_1, \dots, \epsilon_l\}$ of constraints over $\mathcal{V} = \{a_1, \dots, a_n\}$ where each $\epsilon \in A$ is of shape either $a \doteq 1$ or $a \doteq b + c$ or $a \doteq b \cdot c$ for some $a, b, c \in \mathcal{V}$, does there exist a substitution $\zeta : \mathcal{V} \rightarrow \mathbb{N}$ that satisfies A ?*

Reducing Problem 1 to inhabitation in system \mathbf{F} it suffices to axiomatize natural number addition and multiplication. Let us fix an instance of A of Problem 1 over variables $\{a_1, \dots, a_n\}$. In the remainder of this long abstract we sketch the construction of a type environment Δ^A and type τ^A such that A has a solution iff there exists a term M such that $\Delta^A \vdash M : \tau^A$.

To simplify notation, let us define the following types (where $\dagger, \mathbf{1}, \dots$ are standard type variables)

$$\begin{aligned} \dagger \sigma &= \sigma \rightarrow \dagger & U(\sigma) &= (\dagger \sigma \rightarrow \bullet_1) \rightarrow (\sigma \rightarrow \bullet_2) \rightarrow u \\ S(\sigma, \tau, \rho) &= (\dagger \sigma \rightarrow \bullet_1) \rightarrow (\dagger \tau \rightarrow \bullet_2) \rightarrow (\dagger \rho \rightarrow \bullet_3) \rightarrow s \\ P(\sigma, \tau, \rho) &= (\dagger \sigma \rightarrow \bullet_1) \rightarrow (\dagger \tau \rightarrow \bullet_2) \rightarrow (\dagger \rho \rightarrow \bullet_3) \rightarrow p \\ \overline{a \doteq 1} &= P(\mathbf{1}, \mathbf{1}, a) & \overline{a \doteq b + c} &= S(b, c, a) & \overline{a \doteq b \cdot c} &= P(b, c, a) \end{aligned}$$

Intuitively, the type variable $\mathbf{1}$ represents $1 \in \mathbb{N}$, the type $U(\sigma)$ signifies that σ is an element of a universe \mathcal{U} , and $S(\sigma, \tau, \rho)$ (resp. $P(\sigma, \tau, \rho)$) signifies that the sum (resp. product) of the two elements σ and τ is ρ . We axiomatize natural number arithmetic as follows

$$\begin{aligned} \Delta_{\mathbb{N}} &= \{x_u : \forall a. (U(a) \rightarrow \forall b. (U(b) \rightarrow S(a, \mathbf{1}, b) \rightarrow P(b, \mathbf{1}, b) \rightarrow \blacktriangle)) \rightarrow \blacktriangle\}, \\ x_s &: \forall abcde. (U(a) \rightarrow U(b) \rightarrow U(c) \rightarrow U(d) \rightarrow U(e) \rightarrow \\ &S(a, b, c) \rightarrow S(b, \mathbf{1}, d) \rightarrow S(c, \mathbf{1}, e) \rightarrow (S(a, d, e) \rightarrow \blacktriangle) \rightarrow \blacktriangle), \\ x_p &: \forall abcde. (U(a) \rightarrow U(b) \rightarrow U(c) \rightarrow U(d) \rightarrow U(e) \rightarrow \\ &P(a, b, c) \rightarrow S(b, \mathbf{1}, d) \rightarrow S(c, a, e) \rightarrow (P(a, d, e) \rightarrow \blacktriangle) \rightarrow \blacktriangle), y_u^{U(\mathbf{1})} : U(\mathbf{1}), y_p^{P(\mathbf{1}, \mathbf{1}, \mathbf{1})} : P(\mathbf{1}, \mathbf{1}, \mathbf{1}) \} \end{aligned}$$

Type assumptions in $\Delta_{\mathbb{N}}$ encompass the following assertions about members of a universe \mathcal{U}

- $y_u^{U(\mathbf{1})}$ asserts that $\mathbf{1} \in \mathcal{U}$ and $y_p^{P(\mathbf{1}, \mathbf{1}, \mathbf{1})}$ asserts that $\mathbf{1} \cdot \mathbf{1} = \mathbf{1}$
- x_u asserts that for any $a \in \mathcal{U}$ there is $b \in \mathcal{U}$ such that $a + \mathbf{1} = b$ and $b \cdot \mathbf{1} = a$
- x_s asserts for $a, b, c, d, e \in \mathcal{U}$: if $a + b = c$, $b + \mathbf{1} = d$ and $c + \mathbf{1} = e$, then $a + d = e$
- x_p asserts for $a, b, c, d, e \in \mathcal{U}$: if $a \cdot b = c$, $b + \mathbf{1} = d$ and $c + a = e$, then $a \cdot d = e$

Let $\Delta^{\mathbf{A}} = \Delta_{\mathbb{N}} \cup \{x_{\mathbf{A}} : \forall a_1 \dots a_n. (U(a_1) \rightarrow \dots \rightarrow U(a_n) \rightarrow \overline{\mathbf{e}_1} \rightarrow \dots \rightarrow \overline{\mathbf{e}_l} \rightarrow \blacktriangle)\}$ and $\tau^{\mathbf{A}} = \blacktriangle$. We are able to establish soundness (cf. Theorem 1) and completeness (cf. Theorem 2) of our encoding.

Theorem 1 (Soundness). *If $\Delta^{\mathbf{A}} \vdash M : \tau^{\mathbf{A}}$ for some M , then \mathbf{A} has a solution.*

Theorem 2 (Completeness). *If \mathbf{A} has a solution, then $\Delta^{\mathbf{A}} \vdash M : \tau^{\mathbf{A}}$ for some M .*

A rigorous proof of soundness by routine case analysis uses the key property of system **F** that any inhabited type is inhabited by some β -normal η -long Church-style term. The proof of completeness is by direct construction of an inhabitant for a given solution of \mathbf{A} . A formalization of the above reduction is currently under development.

References

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